



Theory of Applied Robotics

Reza N. Jazar

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Theory of Applied Robotics: Kinematics, Dynamics, and Control 2E is appropriate for courses in robotics that emphasize kinematics, dynamics, and control. The contents of this book are presented at a theoretical-practical level. It explains robotics concepts in detail, concentrating on their practical use. Related theorems and formal proofs are provided, as are real-life applications. Students, researchers, and practicing engineers alike will appreciate this user-friendly presentation of a wealth of robotics topics, most notably orientation, velocity, and forward kinematics. The second edition includes updated and expanded exercise sets and problems, new coverage includes, Components and Mechanisms of a Robotic Systems with actuators, sensors and controllers and updated and expanded material on Kinematics including geometric kinematics, Derivative Kinematics, velocity kinematics, and new coverage on sensing and control including position sensors, speed sensors and acceleration sensors.

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